

# EBS862 (Conrac) Power Electronic Unit



For continuous control of Conrac actuators  
RHD(E) ... and RSD(E) ...

Microprocessor-controlled power electronic unit with  
integrated frequency converter

Voltage supply 230 V AC

Conventional signal interface (0 / 4 ... 20 mA / 24 V)

Digital communication via RS232 and HART

Additional functions such as process controller,  
maintenance computer, programmable characteristics

Rack installation, protection class IP 20

Torque and speed variation

Continuous positioning

Simple installation and commissioning

Simple configuration and parameter setting via graphical  
user interface

High response sensitivity

Reliable for short positioning times

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## 1 Concept

Compact actuator for the operation of final control elements with preferably 90° rotary movement such as flaps, cocks, etc.

The torque is transferred via a lever / linkage bar assembly or the actuator is directly coupled to the cock flange.

A special power electronic unit controls the actuator. The electronic unit serves as the interface between actuator and control system.

During continuous positioning the power electronic unit varies the motor torque steplessly until the actuator force and the restoring

process forces are balanced. High response sensitivity and high positioning accuracy with short positioning time ensure an excellent control quality and a long actuator life.



### Important

The ANSI information appears in parentheses after the SI-information.

## 2 Technical data

Supply voltage (standard actuators)	230 V AC (190 ... 260 V); 47.5 ... 63 Hz; 1 Ph		
Supply voltage (Ex actuators)	230 V AC (190 ... 253 V); 47.5 ... 63 Hz; 1 Ph		
Current at electronic unit [A] (AC 230 V AC)		$I_{max.}$ at 230 V	$I_{pos.}$ (230 V) approx. 40 ... 50% of $I_{max.}$
	RHD(E)2500-10	5.3 A	
	RHD(E)4000-10	10.0 A	
	RHD8000-12	8.0 A	
	RHDE8000-15	8.0 A	
	RHD(E)16000-30	12.5 A	
	RSD(E)50-10.0	6.4 A	
	RSD100-10.0	12.5 A	
	RSD200-5.0	13.0 A	
External fuse	safety fuse 35 A (Lindner) + thermal circuit breaker 16 A (ETA) (fuse and circuit breaker are part of shipment)		
External fuse for heat supply	2 ... 6 A; medium time-lag		
Analog input	0 / 4 ... 20 mA		
Analog output	0 / 4 ... 20 mA, galvanically isolated		
3 binary inputs BE 1 ... BE 3 (DI 1 ... DI 3)	Binary 0: -3 ... 5 V or open, galvanically separated Binary 1: 12 ... 35 V, galvanically separated		
3 binary outputs BA 1 ... BA 3 (DO 1 ... DO 3)	Potential free relay contact, max. 60 V, 150 mA		
Digital communication	RS232 for commissioning and service, optionally FSK / HART®		
Default settings	Behavior in 0 / 100 % end position:	Hold with rated torque / end positions	
	set point function:	linear, set point = position value	
	set point input:	4 ... 20 mA	
	function selection:	positioner, parameter: setpoint	
	actual value:	4 ... 20 mA	
	digital input:	BE 1 (DI 1) M / A selection; BE 2 / 3 (DI 2 / 3) manual intervention +/-	
	digital output:	BA 1 (DO 1) ready for operation; BA 2 / 3 (DO 2 / 3) end position signal 0 / 100 %	
	positioning time-out	not activated for standard actuators always activated for actuators in explosion proof design	
Voltage output $U_V$	24 V, 15 mA, galvanically isolated; e.g., for scanning external contacts		
Transmitter (optional)	Supply for 2-wire transmitter with activated process controller in Contrac		
Individual settings	See data sheet 10/68-2.40 or upon request		

### 2.1 General information

Power Electronic Unit EBS862 (Contrac)	
Protection Class	IP 20
Humidity	≤ 75 % annual average (condensation not permitted)
Rack inlet temperature	0 ... 45 °C (32 ... 110 °F)
Mounting position	at vertical support, cable glands at the bottom
Coating	2-layer component epoxy (RAL 9005, black)
Cable between actuator and electronic unit	max. cable length: 470 m (1542 ft) , depending on actuator model and cable gauge; for additional information, refer to the operating instructions for the electronic unit
Electrical connection	mains supply via terminals; others via pluggable terminals
Weight; approx.	40 kg (88 lb)

## 3 Electrical connection

### 3.1 Standard actuators



**Important**

The electrical connection is provided by a plug on the actuator and the terminals on the electronic unit.

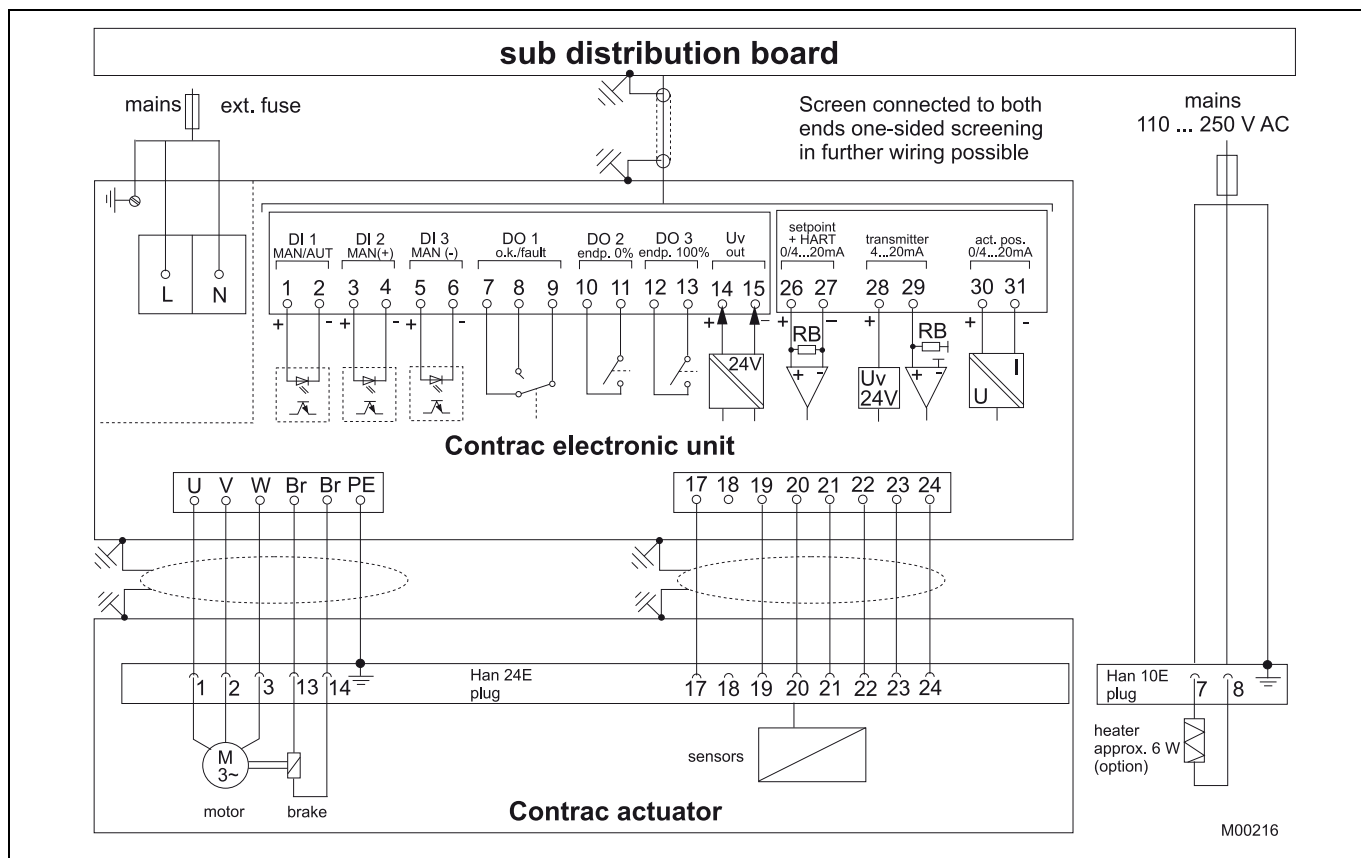


Fig. 1

### 3.2 Ex actuators



**Important**

The electrical connection is provided by terminals on the actuator and on the electronic unit.

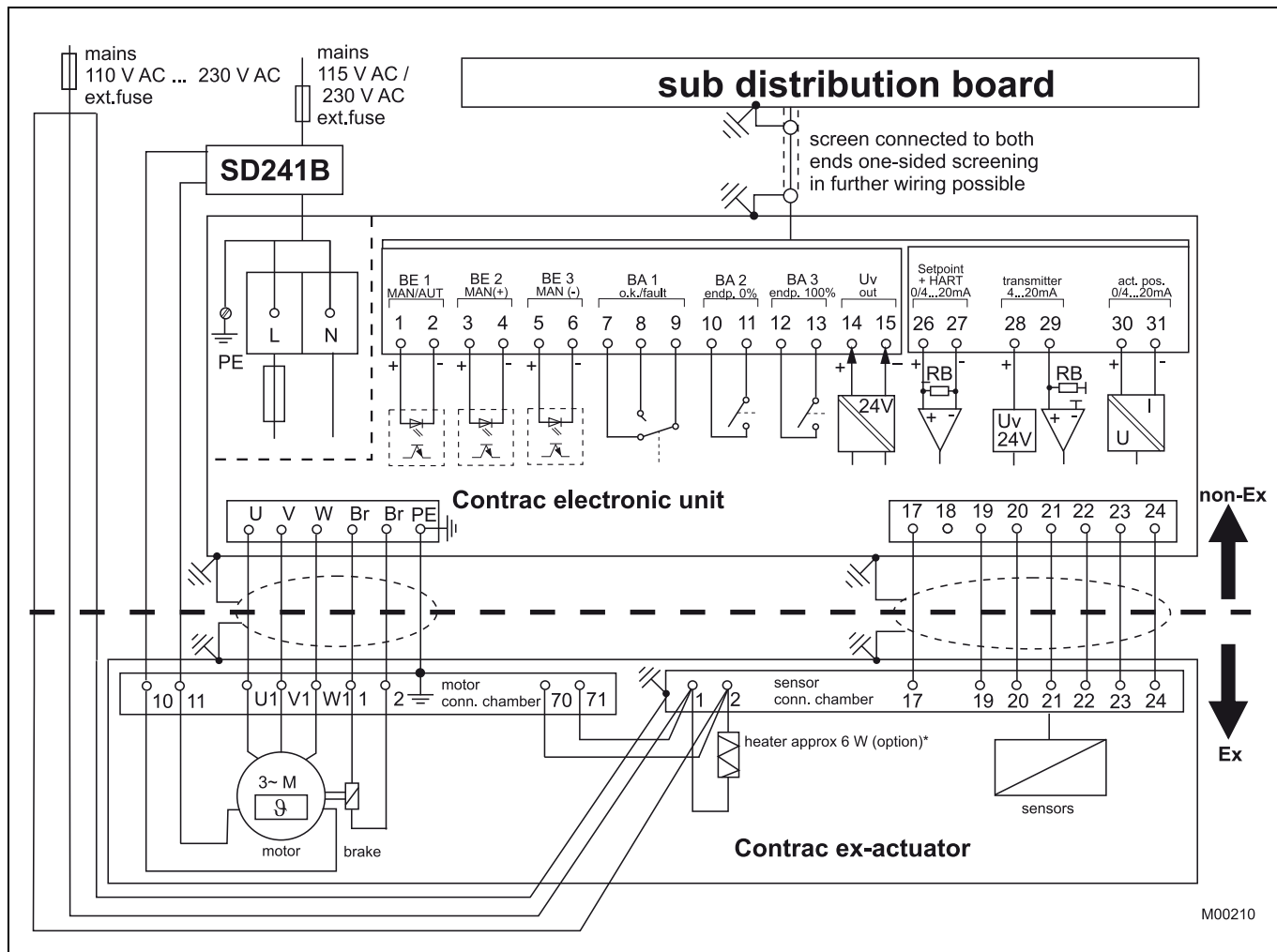


Fig. 2: Electrical connection: Ex actuator analog / binary



**Important**

\* For separate heat supply, protect the heater with 2 ... max. 6 A medium time-lag fuses (e.g., Neozed D01CE14).



**Installation information on the cable harness for actuators in Ex design**

The electrical connection between the Contrac electronic unit and the Contrac actuator can be established using the cable harness (order code 695). The cable harness is not part of the Ex prototype test certificate and must therefore be tested for safety-relevant functionality within the complete installation by the installer or operator.

If the specified cable harness does not meet all safety-relevant requirements, the proper installation material must be used.

For the specified motor connecting cable, the screen must be connected at both ends and grounded.

## 4 Dimensions

### 4.1 Power Electronic Unit

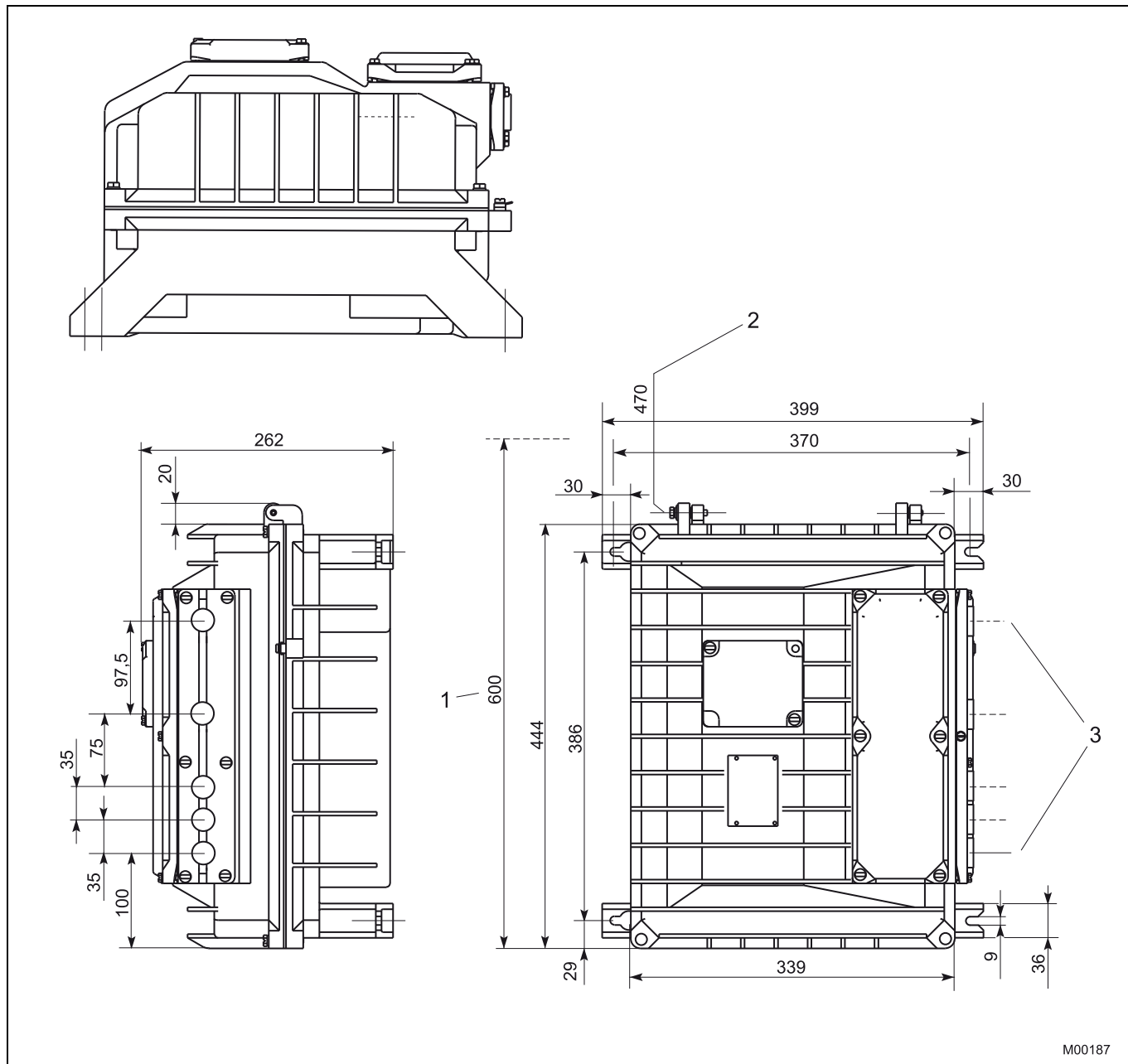


Fig. 3: Dimensions in mm

- 1 front section open, rotated 90°  
 2 rotational radius

- 3 tap holes

Max. cable gauge		Tap holes for cable glands	
mains; motor	solid wire: 6 mm <sup>2</sup>		metric
	flexible: 4 mm <sup>2</sup>	mains	1 x M20 x 1.5
signal	solid wire: 4 mm <sup>2</sup>	signal	3 x M20 x 1.5
	flexible: 2,5 mm <sup>2</sup>	motor	1 x M25 x 1.5

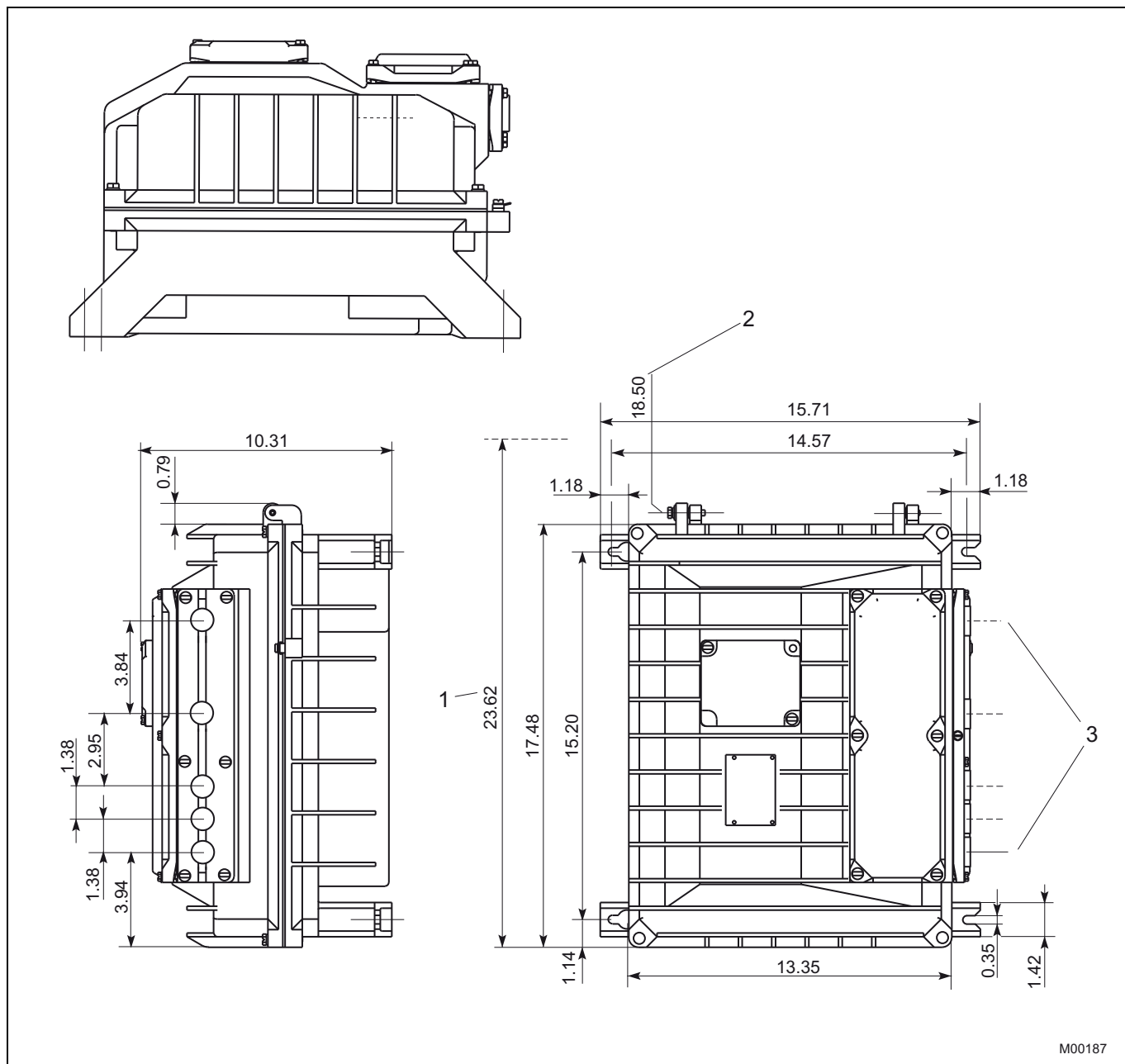


Fig. 4: Dimensions in inches

- 1 front section open, rotated 90°
- 2 rotational radius

- 3 tap holes

Max. cable gauge		Tap holes for cable glands	
mains; motor	solid wire: 10 AWG	mains	metric
	flexible: 12 AWG		1 x M20 x 1.5
signal	solid wire: 12 AWG	signal	3 x M20 x 1.5
	flexible: 14 AWG	motor	1 x M25 x 1.5

4.2 Fuses

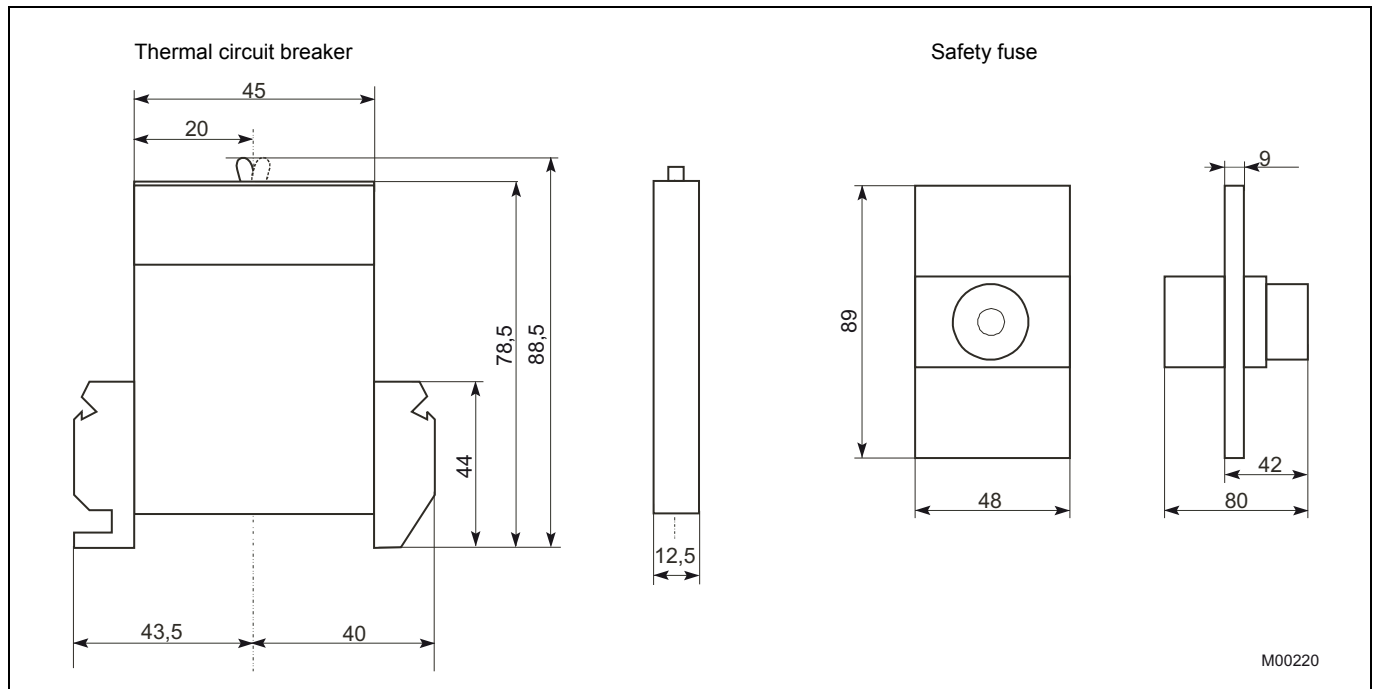


Fig. 5: Dimensions in mm

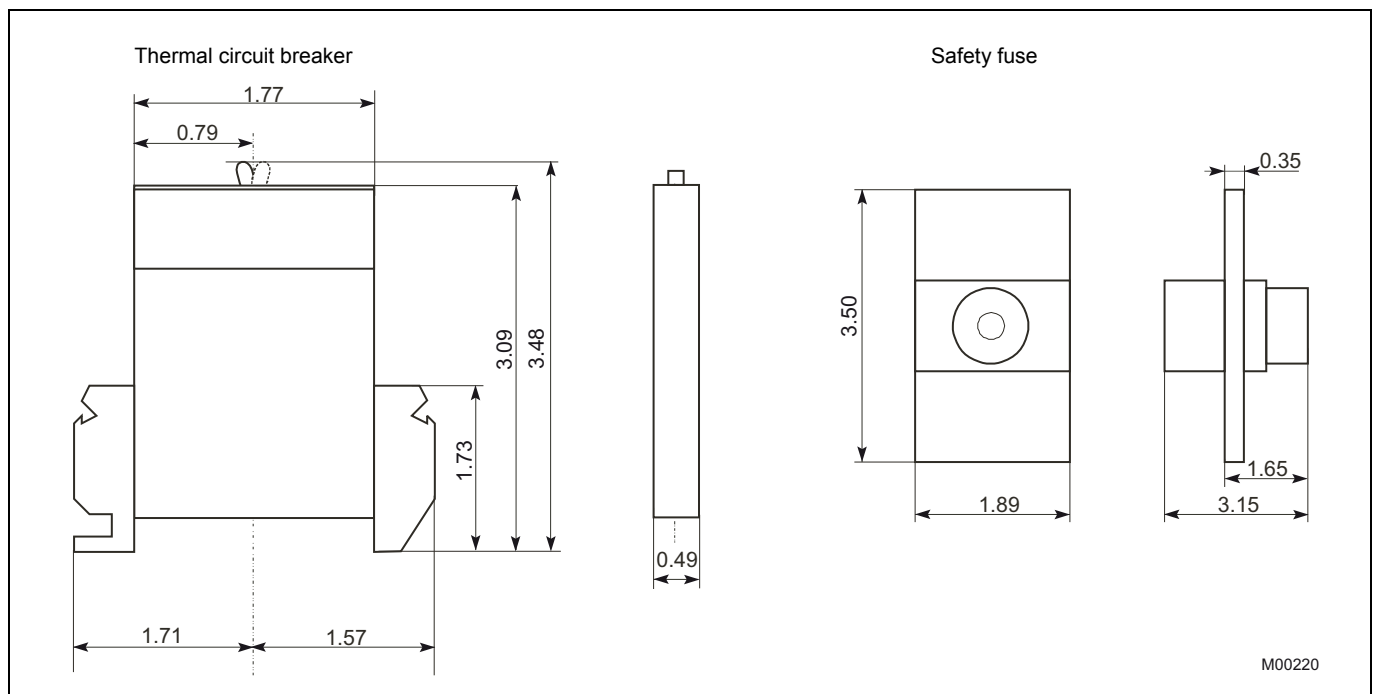


Fig. 6: Dimensions in inches

## 5 Ordering information

### 5.1 Standard actuators

Electronic Unit		Variant digit No.				Code				
EBS862		1 - 8	9	10	11 12					
		Catalog No. <b>V68862A-</b>								
<b>Suitable for</b>										
<b>Linear Actuator</b>	Force	Speed		Stroke						
RSD50-10,0/120	50 kN (11240 lbs)	10.0 mm/s	(2.5 s/in)	120 mm	(4.7 in)	3	0	7	3	
RSD50-10,0/300	50 kN (11240 lbs)	10.0 mm/s	(2.5 s/in)	300 mm	(11.8 in)	9	1	7	3	
RSD100-10,0/150	100 kN (22500 lbs)	10.0 mm/s	(2.5 s/in)	150 mm	(5.9 in)	2	1	7	4	
RSD100-10,0/300	100 kN (22500 lbs)	10.0 mm/s	(2.5 s/in)	300 mm	(11.8 in)	9	1	7	4	
RSD200-5,0/180	200 kN (45000 lbs)	5.0 mm/s	(5.0 s/in)	180 mm	(7.08 in)	5	4	7	5	
RSD200-5,0/300	200 kN (45000 lbs)	5.0 mm/s	(5.0 s/in)	300 mm	(11.8 in)	9	1	7	5	
<b>Part-Turn Actuator</b>	Torque	Speed								
RHD2500-10	2500 Nm (1900 ft-lbs)	9.0 °/s				0	1	1	5	
RHD4000-10	4000 Nm (3000 ft-lbs)	9.0 °/s				0	1	1	6	
RHD8000-12	8000 Nm (6000 ft-lbs)	7.5 °/s				0	1	7	0	
RHD16000-30	16000 Nm (12000 ft-lbs)	3.0 °/s				0	1	1	8	
<b>Special features of Electronic Unit</b>										
Select at least one feature per group										
<b>Supply voltage</b>	230 V AC 1 Ph					380				
<b>Frequency</b>	50 Hz					382				
	60 Hz					383				
<b>Digital communication</b>	RS 232					384				
	RS 232 + HART					385				
<b>Ambient temperature range of actuator</b>	-30 ... 50 °C (-20 ... 130 °F)					341				
	-10 ... 65 °C (15 ... 150 °F)					344				
<b>Settings of electronic unit</b>	Standard settings				(see techn. data)	390				
	Customer specific settings				(see data sheet 10/68-2.40 EN)	391				

<b>Additional ordering information</b>										
						Code				
Anti-condensation heater in actuator "ON"						359				
Identification on data label (alphanumeric, max. 32 characters)						295				
Data label with US units						253				
F. No. of associated actuator on data label of electronic unit						297				
Factory certificate 2.1 acc. to EN 10204						291				
Certificate B acc. to EN 10204						292				
<b>Operating instruction</b>	(specify total quantity required, 1 copy without extra charge)									
	German	(no specification for 1 copy)				Z1D				
	English	(always state Code-No.)				Z1E				

## 5.2 Ex actuators

Electronic Unit		Variant digit No.		1 - 8		9 10 11 12		Code				
<b>EBS862</b>		Catalog No.		<b>V68862A-</b>								
<b>Suitable for</b>												
<b>Linear Actuator</b>		Force	Speed		Stroke							
RSDE50-10,0/120	50 kN (11000 lbs)	10.0 mm/s (2.5 s/in)	120 mm (4.7 in)		3 0 8 4							
RSDE50-10,0/300	50 kN (11000 lbs)	10.0 mm/s (2.5 s/in)	300 mm (11.8 in)		9 1 8 4							
RSDE100-10,0/150	100 kN (22000 lbs)	10.0 mm/s (2.5 s/in)	150 mm (5.9 in)		2 1 8 6							
RSDE100-10,0/300	100 kN (22000 lbs)	10.0 mm/s (2.5 s/in)	300 mm (11.8 in)		9 1 8 6							
<b>Part-Turn Actuator</b>		Torque		Speed								
RHDE2500-10	2500 Nm (1850 ft-lbs)	9.0 °/s		0 1 5 9								
RHDE4000-10	4000 Nm (2950 ft-lbs)	9.0 °/s		0 1 6 0								
RHDE8000-15	8000 Nm (5900 ft-lbs)	6.0 °/s		0 1 6 8								
RHDE16000-30	16000 Nm (11800 ft-lbs)	3.0 °/s		0 1 6 9								
<b>Special features of Electronic Unit</b>												
Select at least one feature per group												
<b>Supply voltage</b>		230 V AC 1 Ph					380					
<b>Frequency</b>		50 Hz					382					
		60 Hz					383					
<b>Digital communication</b>		RS 232					384					
		RS 232 + HART					385					
<b>Ambient temperature range of actuator</b>		-25 ... 60°C (-13 ... 140°F)		(only for part turn actuators Ex)		346						
		-30 ... 40°C (-22 ... 104°F)		(only for part turn actuators Ex)		347						
		-20 ... 60°C (-4 ... 140°F)		(only for linear actuators Ex)		348						
<b>Settings of electronic unit</b>		Standard settings		(see techn. data)		390						
		Customer specific settings		(see data sheet 10/68-2.40 EN)		391						

<b>Additional ordering information</b>											
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German		(no specification for 1 copy)					Z1D				
English		(always state Code-No.)					Z1E				



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