

IRC5 Compact controller Optimised for small robots

The IRC5 Compact controller extends the comprehensive IRC5 family of robot controllers. It brings the familiar benefits of the world leading robot controller, including superior motion control and flexible RAPID language, while adding the advantage of a minimised footprint.

IRC5 Compact

The IRC5 Compact offers the capabilities of the extremely powerful IRC5 controller in a truly compact format. In addition, the IRC5 Compact delivers space saving benefits and easy commissioning through one phase power input, external connectors for all signals and a built in expandable 16 in, 16 out I/O system.

Utilising many of the well-known features of the IRC5 controller, the compact version offers familiar programming and operation, ensuring no additional training is required.

The IRC5 Compact controller is available for the lower end robots of the IRB range.

Safety

Operator safety is a central quality of the IRC5 Compact, fulfilling all relevant regulations, as certified by third-party inspections.

Motion Control

Based on advanced dynamic modeling, the IRC5 optimizes the performance of the robot for the shortest possible cycle time (QuickMove) and precise path accuracy (TrueMove). Together with a speed independent path, predictable and high performance behaviour is delivered automatically, with no tuning required by the programmer. What you program is what you get!

FlexPendant

The FlexPendant is characterised by its clean, colour touch screen-based design and 3D joystick for intuitive interaction. Powerful customized application support enables loading of tailor-made applications, for example operator screens, thus eliminating the need for a separate operator HMI.



RAPID programming language

RAPID programming provides the perfect combination of simplicity, flexibility and power. It is a truly unlimited language with support for structured programs, shop floor language and advanced features. It also incorporates powerful support for many process applications.

Communication

The IRC5 supports the state-of-the-art field busses for I/O and is a well-behaved node in any plant network. Sensor interface functionality, remote disk access and socket messaging are examples of the many powerful networking features.

Remote service enabled

Remote monitoring of the robot is available through standard communication networks (GSM or Ethernet). Advanced diagnostic methods allow fast investigation on failure as well as monitoring of the robot condition throughout the life cycle. Service packages are available, including new services like backup management, reporting and proactive maintenance activities.

RobotStudio

RobotStudio is a powerful PC tool for working with IRC5 data. It can be used offline, providing a perfect digital copy of the automation system together with strong programming and simulation features.

IRC5 Compact

Specification

Controller hardware:	Multi-processor system PCI bus Flash disk mass memory Energy back-up power failure handling USB memory interface
Control software:	Well proven real-time OS High-level RAPID programming language PC-DOS file format Preloaded software, available on DVD Extensive functionality set, see separate RobotWare data sheet

Electrical Connections

Supply voltage:	Single phase 220/230 V, 50-60 Hz
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Physical

	Size HxWxD	Weight
	258 x 450 x 580	28.5 kg

Environment

Ambient temperature:	+ 0° C (32°F) - +45°C (113°F)
Relative humidity	Max. 95%
Level of protection	IP20
Fulfilment of regulations	Machine directive 98/37/EC regulation Annex II B EN 60204-1:2006 ISO 10218-1:2006 ANSI/RIA R 15.06 -1999

User Interfaces

Control panel	On cabinet or remote
FlexPendant	Weight 1 kg Graphical color touch screen Joystick Emergency stop Support for right- and left hand operators USB Memory support
Maintenance	Diagnostic software Recovery procedure Logging with time stamp Remote Service enabled

Supported robots

IRB 120
IRB 140
IRB 260
IRB 360
IRB 1410
IRB 1600

Safety

Basic:	Safety and emergency stops 2-channel safety circuits supervision 3-position enabling device
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Machine Interfaces

Inputs/outputs:	Standard 16/16 (up to 2200)
Digital:	24V DC or relay signals
Analogue:	2 x 0-10V, 3x ±10V, 1x4-20mA
Serial channel:	1 x RS 232 (RS422 with adaptor)
Network:	Ethernet (10/100 Mbits per second)
Two channels:	Service and LAN
Fieldbus Master:	DeviceNet™ PROFIBUS DP Ethernet/IP™
Fieldbus Slave:	PROFINET PROFIBUS DP Ethernet/IP™ Allen-Bradley Remote I/O CC-link
Conveyor encoder	Up to 6 channels

Sensor Interfaces

Search stop with automatic program shift
Seam/contour tracking
Conveyor tracking
Machine vision
Force control

Data and dimensions may be changed without notice